

# A New Connection Between Node and Edge Depth Robust Graphs

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## Abstract

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Given a directed acyclic graph (DAG)  $G = (V, E)$ , we say that  $G$  is  $(e, d)$ -depth-robust (resp.  $(e, d)$ -edge-depth-robust) if for any set  $S \subset V$  (resp.  $S \subseteq E$ ) of at most  $|S| \leq e$  nodes (resp. edges) the graph  $G - S$  contains a directed path of length  $d$ . While edge-depth-robust graphs are potentially easier to construct many applications in cryptography require node depth-robust graphs with small indegree. We create a graph reduction that transforms an  $(e, d)$ -edge-depth-robust graph with  $m$  edges into a  $(e/2, d)$ -depth-robust graph with  $O(m)$  nodes and constant indegree. One immediate consequence of this result is the first construction of a provably  $(\frac{n \log \log n}{\log n}, \frac{n}{(\log n)^{1+\log \log n}})$ -depth-robust graph with constant indegree, where previous constructions for  $e = \frac{n \log \log n}{\log n}$  had  $d = O(n^{1-\epsilon})$ . Our reduction crucially relies on ST-Robust graphs, a new graph property we introduce which may be of independent interest. We say that a directed, acyclic graph with  $n$  inputs and  $n$  outputs is  $(k_1, k_2)$ -ST-Robust if we can remove any  $k_1$  nodes and there exists a subgraph containing at least  $k_2$  inputs and  $k_2$  outputs such that each of the  $k_2$  inputs is connected to all of the  $k_2$  outputs. If the graph is  $(k_1, n - k_1)$ -ST-Robust for all  $k_1 \leq n$  we say that the graph is maximally ST-robust. We show how to construct maximally ST-robust graphs with constant indegree and  $O(n)$  nodes. Given a family  $\mathbb{M}$  of ST-robust graphs and an arbitrary  $(e, d)$ -edge-depth-robust graph  $G$  we construct a new constant-indegree graph  $\text{Reduce}(G, \mathbb{M})$  by replacing each node in  $G$  with an ST-robust graph from  $\mathbb{M}$ . We also show that ST-robust graphs can be used to construct (tight) proofs-of-space and (asymptotically) improved wide-block labeling functions.

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## 1 Introduction

Given a directed acyclic graph (DAG)  $G = (V, E)$ , we say that  $G$  is  $(e, d)$ -reducible (resp.  $(e, d)$ -edge reducible) if there is a subset  $S \subseteq V$  (resp.  $S \subseteq E$ ) of  $|S| \leq e$  nodes (resp. edges) such that  $G - S$  does not contain a directed path of length  $d$ . If a graph is not  $(e, d)$ -reducible (resp.  $(e, d)$ -edge reducible) we say that the graph is  $(e, d)$ -depth robust (resp.  $(e, d)$ -edge-depth-robust). Depth robust graphs have found many applications in the field of cryptography in the construction of proofs of sequential work [11], proofs of space [7, 12], and in the construction of data independent memory hard functions (iMHFs). For example, highly depth robust graphs are known to be necessary [1] and sufficient [3] to construct



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iMHF's with high amortized space time complexity. While edge depth-robust graphs are often easier to construct [14], most applications require node depth-robust graphs with small indegree.

It has been shown [17] that in any DAG with  $m$  edges and  $n$  nodes and any  $i \leq \log_2 n$ , there exists a set  $S_i$  of  $\frac{mi}{\log n}$  edges that will destroy all paths of length  $n/2^i$  forcing  $\text{depth}(G - S_i) \leq \frac{n}{2^i}$ . For DAGs with constant indegree we have  $m = O(n)$  edges so an equivalent condition holds for node depth robustness [1], since a node can be removed by removing all the edges incident to it. In particular, there exists a set  $S_i$  of  $O(\frac{ni}{\log n})$  nodes such that  $\text{depth}(G - S_i) \leq \frac{n}{2^i}$  for all  $i < \log n$ . It is known how to construct an  $(c_1 n / \log n, c_2 n)$ -depth-robust graph, for suitable  $c_1, c_2 > 0$  [3] and an  $(c_3 n, c_4 n^{1-\epsilon})$ -depth-robust graph for small  $\epsilon$  for [14].

An open challenge is to construct constant indegree  $(c_1 ni / \log n, c_2 n / 2^i)$ -depth-robust graphs which match the Valiant bound [17] for intermediate values of  $i = \omega(1)$  and  $i = o(\log n)$ . For example, when  $i = \log \log n$  then the Valiant bound [17] does not rule out the existence of  $(c_1 ni / \log n, c_2 n / \log n)$ -depth-robust graphs with constant indegree. Such a graph would yield asymptotically stronger iMHFs [5]. While there are several constructions that are conjectured to be  $(c_1 ni / \log n, c_2 n / \log n)$ -depth-robust the best provable lower bound for  $(e = cni / \log n, d)$ -depth robustness of a constant indegree graph is  $d = \Omega(n^{1-\epsilon})$ . For edge-depth robustness we have constructions of graphs with  $m = O(n \log n)$  edges which are  $(e_i, d_i)$ -edge depth robust for any  $i$  with  $e_i = mi / \log n$  and  $d_i = n / \log^{i+1} n$  – much closer to matching the Valiant bound [17].

## 1.1 Contributions

Our main contribution is a graph reduction that transforms any  $(e, d)$ -edge-depth-robust graph with  $m$  edges into a  $(e/2, d)$ -depth-robust graph with  $O(m)$  nodes and constant indegree. Our reduction utilizes ST-Robust graphs, a new graph property we introduce and construct. We believe that ST-Robust graphs may be of independent interest.

Intuitively, a  $(k_1, k_2)$ -ST-Robust graph with  $n$  inputs  $I$  and  $n$  outputs  $O$  satisfies the property that, even after deleting  $k_1$  nodes from the graph we can find  $k_2$  inputs  $x_1, \dots, x_{k_2}$  and  $k_2$  outputs  $y_1, \dots, y_{k_2}$  such that every input  $x_i$  ( $i \in [k_2]$ ) is still connected to every output  $y_j$  ( $j \in [k_2]$ ). If we can guarantee that the each directed path from  $x_i$  to  $y_j$  has length  $d$  then we say that the graph is  $(k_1, k_2, d)$ -ST-Robust. A maximally depth-robust graph should be  $(k_1, n - k_1)$ -depth robust for any  $k_1$ .

► **Definition 1 (ST-Robust).** Let  $G = (V, E)$  be a DAG with  $n$  inputs, denoted by set  $I$  and  $n$  outputs, denoted by set  $O$ . Then  $G$  is  $(k_1, k_2)$ -ST-robust if  $\forall D \subset V(G)$  with  $|D| \leq k_1$ , there exists subgraph  $H$  of  $G - D$  with  $|I \cap V(H)| \geq k_2$  and  $|O \cap V(H)| \geq k_2$  such that  $\forall s \in I \cap V(H)$  and  $\forall t \in O \cap V(H)$  there exists a path from  $s$  to  $t$  in  $H$ . If  $\forall s \in I \cap V(H)$  and  $\forall t \in O \cap V(H)$  there exists a path from  $s$  to  $t$  of length  $\geq d$  then we say that  $G$  is  $(k_1, k_2, d)$ -ST-robust.

► **Definition 2 (Maximally ST-Robust).** Let  $G = (V, E)$  be a constant indegree DAG with  $n$  inputs and  $n$  outputs. Then  $G$  is  $c_1$ -maximally ST-robust (resp.  $c_1$  max ST-robust with depth  $d$ ) if there exists a constant  $0 < c_1 \leq 1$  such that  $G$  is  $(k, n - k)$ -ST-robust (resp.  $(k, n - k, d)$ -ST-robust) for all  $k$  with  $0 \leq k \leq c_1 n$ . If  $c_1 = 1$ , we just say that  $G$  is maximally ST-Robust.

We show how to construct maximally ST-robust graphs with constant indegree and  $O(n)$  nodes and we show how maximally ST-robust graphs can be used to transform any  $(e, d)$ -edge-depth-robust graph  $G$  with  $m$  edges into a  $(e/2, d)$ -depth-robust graph  $G'$  with

$O(m)$  nodes and constant indegree. Intuitively, in our reduction each node  $v \in V(G)$  with degree  $\delta(v)$  is replaced with a maximally ST-robust graph  $M_{\delta(v)}$  with  $\delta(v)$  inputs/outputs. Incoming edges into  $v$  are redirected into the inputs  $I_{\delta(v)}$  of the ST-robust graph. Similarly,  $v$ 's outgoing edges are redirected out of the outputs  $O_{\delta(v)}$  of the ST-robust graph. Because  $M_{\delta(v)}$  is maximally ST-robust, when a node is removed from  $M_{\delta(v)}$  the set of inputs and outputs where each input connects to every output has at most one input and one output node removed. Each input or output node removed from  $M_{\delta(v)}$  corresponds to removing at most one edge from the original graph. Thus, removing  $k$  nodes from  $M_{\delta(v)}$  corresponds to destroying at most  $2k$  edges in the original graph  $G$ .

Our reduction gives us a fundamentally new way to design node-depth-robust graphs: design an edge-depth-robust graph (easier) and then reduce it to a node-depth-robust graph. The reduction can be used with a construction from [14] to construct a  $(\frac{n \log \log n}{\log n}, \frac{n}{(\log n)^{1+\log \log n}})$ -depth-robust graph. We conjecture that several prior DAG constructions (e.g. [4, 8, 14]) are actually  $(n \log \log n, \frac{n}{\log n})$ -edge-depth-robust. If any of these conjectures are true then our reduction would immediately yield the desired  $(\frac{n \log \log n}{\log n}, \frac{n}{\log n})$ -depth-robust graph.

We also present several other applications for maximally ST-robust graphs including (tight) proofs-of-space and wide block-labeling functions.

## 2 Edge to Node Depth-Robustness

In this section, we use the fact that linear sized, constant indegree, maximally ST-robust graphs exist to construct a transformation of an  $(e, d)$ -edge-depth robust graph with  $m$  edges into an  $(e, d)$ -node-depth robust graph with constant indegree and  $O(m)$  nodes. In the next section we will construct a family of ST-robust graphs that satisfies Theorem 3.

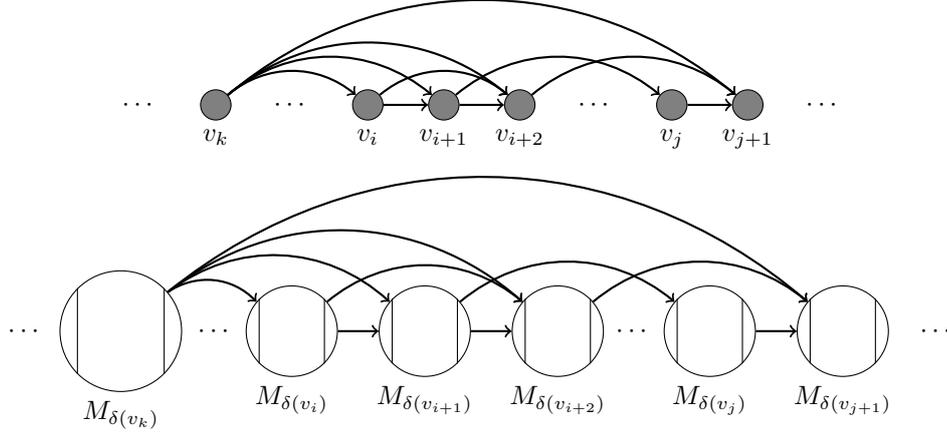
► **Theorem 3** (Key Building Block). *There exists a family of graphs  $\mathbb{M} = \{M_n\}_{n=1}^{\infty}$  with the property that for each  $n \geq 1$ ,  $M_n$  has constant indegree,  $O(n)$  nodes, and is maximally ST-Robust.*

### 2.1 Reduction Definition

Let  $G = (V, E)$  be a DAG, and let  $\mathbb{M}$  be as in Theorem 3. Then we define  $\text{Reduce}(G, \mathbb{M})$  in construction 4 as follows:

► **Construction 4** ( $\text{Reduce}(G, \mathbb{M})$ ). *Let  $G = (V, E)$  and let  $\mathbb{M}$  be the family of graphs defined above. For each  $M_n \in \mathbb{M}$ , we say that  $M_n = (V(M_n), E(M_n))$ , with  $V(M_n) = I(M_n) \cup O(M_n) \cup D(M_n)$ , where  $I(M_n)$  are the inputs of  $M_n$ ,  $O(M_n)$  are the outputs, and  $D(M_n)$  are the internal vertices. For  $v \in V$ , let  $\delta(v) = \max\{\text{indegree}(v), \text{outdegree}(v)\}$ . Then we define  $\text{Reduce}(G) = (V_R, E_R)$ , where  $V_R = \{(v, w) | v \in V, w \in V(M_{\delta(v)})\}$  and  $E_R = E_{\text{internal}} \cup E_{\text{external}}$ . We let  $E_{\text{internal}} = \{(v, u'), (v, w') | v \in V, (u', w') \in E(M_{\delta(v)})\}$ . Then for each  $v \in V$ , we define an  $\text{In}(v) = \{u : (u, v) \in E\}$  and  $\text{Out}(v) = \{u : (v, u) \in E\}$  and then pick two injective mappings  $\pi_{\text{in},v} : \text{In}(v) \rightarrow I(V(M_{\delta(v)}))$  and  $\pi_{\text{out},v} : \text{Out}(v) \rightarrow O(V(M_{\delta(v)}))$ . We let  $E_{\text{external}} = \{((u, \pi_{\text{out},u}(v)), (v, \pi_{\text{in},v}(u))) : (u, v) \in E\}$ .*

*Intuitively, to construct  $\text{Reduce}(G, \mathbb{M})$  we replace every node of  $G$  with a constant indegree, maximally ST-robust graph, mapping the edges connecting two nodes from the outputs of one ST-robust graph to the inputs of another. Then for every  $e = (u, w) \in E$ , add an edge from an output of  $M_{\delta(u)}$  to an input of  $M_{\delta(w)}$  such that the outputs of  $M_{\delta(u)}$  have outdegree at most 1, and the inputs of  $M_{\delta(w)}$  have indegree at most 1. If  $v \in V$  is replaced by  $M_{\delta(v)}$ , then we call  $v$  the genesis node and  $M_{\delta(v)}$  its metanode.*



■ **Figure 1** Diagram of the transformation  $\text{Reduce}(G, \mathbb{M})$ .

## 2.2 Proof of Main Theorem

We now state the main result of this section which says that if  $G$  is edge-depth robust then  $\text{Reduce}(G, \mathbb{M})$  is node depth-robust.

► **Theorem 5.** *Let  $G$  be an  $(e, d)$ -edge-depth-robust DAG with  $m$  edges. Let  $\mathbb{M}$  be a family of max ST-Robust graphs with constant indegree. Then  $G' = (V', E') = \text{Reduce}(G, \mathbb{M})$  is  $(e/2, d)$ -depth robust. Furthermore,  $G'$  has maximum indegree  $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$ , and its number of nodes is  $\sum_{v \in V(G)} |V(M_{\delta(v)})|$  where  $\delta(v) = \max\{\text{indeg}(v), \text{outdeg}(v)\}$ .*

A formal proof can be found in Appendix B. We briefly outline the intuition for this proof below.

**Proof (Intuition).** The first thing we note is that each graph  $M_{\delta(v)}$  has constant indegree at most  $c\delta(v)$  nodes for some constant  $c > 0$ . Therefore, the graph  $G'$  has  $\sum_{v \in V(G)} |V(M_{\delta(v)})| \leq c \sum_v \delta(v) \leq 2cm$  nodes and  $G'$  has constant indegree.

Now for any set  $S \subseteq V'$  of nodes we remove from  $G'$  we will map  $S$  to a corresponding set  $S_{irr} \subseteq E$  of at most  $|S_{irr}| \leq 2|S|$  irreparable edges in  $G$ . We then prove that any path  $P$  in  $G - S_{irr}$  corresponds to a longer path  $P'$  in  $G' - S$  that is at least as long. Intuitively, each incoming edge  $(u, v)$  (resp. outgoing edge  $(v, w)$ ) in  $E(G)$  corresponds to an input node (resp. output node) in  $v$ 's corresponding metanode  $M_{\delta(v)}$  which we will label  $x_{u,v}$  (resp.  $y_{v,w}$ ). If  $S \subseteq V'$  removes at most  $k$  nodes from the metanode  $M_{\delta(v)}$  then, by maximal ST-robustness, we still can find  $\delta(v) - k$  inputs and  $\delta(v) - k$  outputs that are *all* pairwise connected. If  $x_{u,v}$  (resp.  $y_{v,w}$ ) is not part of this pairwise connected subgraph then we will add the corresponding edge  $(u, v)$  (resp.  $(v, w)$ ) to the set  $S_{irr}$ . Thus, the set  $S_{irr}$  will have size at most  $2|S|$  Claim 30 in the appendix).

Intuitively, any path  $P$  in  $G - S_{irr}$  can be mapped to a longer path  $P'$  in  $G' - S$  (Claim 29). If  $P$  contains the edges  $(u, v), (v, w)$  then we know that the input node  $x_{u,v}$  and output node  $y_{v,w}$  node in  $M_{\delta(v)}$  are still connected in  $G' - S$ . ◀

► **Corollary 6** (of Theorem 5). *If there exists some constants  $c_1, c_2$ , such that we have a family  $\mathbb{M} = \{M_n\}_{n=1}^{\infty}$  of linear sized  $|V(M_n)| \leq c_1 n$ , constant indegree  $\text{indeg}(M_n) \leq c_2$ , and maximally ST-Robust graphs, then  $\text{Reduce}(G, \mathbb{M})$  has maximum indegree  $c_2$  and the number of nodes is at most  $2c_1 m$ .*

The next corollary states that if we have a family of maximally ST-Robust graphs with  $\mathbb{M} = \{M_k\}_{k=1}^\infty$  depth  $d_k$  then we can transform any  $(e, d)$ -edge-depth-robust DAG  $G = (V, E)$  with maximum degree  $\delta = \max_{v \in V} \delta(v)$  into  $(e/2, d \cdot d_\delta)$ -depth robust graph. Instead of replacing each node  $v \in G$  with a copy of  $M_{\delta(v)}$ , we instead replace each node with a copy of  $M_{\delta, v} := M_\delta$ , attaching the edges same way as in Construction 4. Thus the transformed graph  $G'$  has  $|V(G)| \times |M_\delta|$  nodes and constant indegree. Intuitively, any path  $P$  of length  $d$  in  $G - S_{irr}$  now maps to a path  $P'$  of length  $d \times d_\delta$  – if  $P$  contains the edges  $(u, v), (v, w)$  then we know that the input node  $x_{u,v}$  and output node  $y_{u,v}$  node in  $M_{\delta, v}$  are connected in  $G' - S$  by a path of length at least  $d_\delta$ .

► **Corollary 7** (of Theorem 5). *Suppose that there exists a family  $\mathbb{M} = \{M_k\}_{k=1}^\infty$  of max ST-Robust graphs with depth  $d_k$  and constant indegree. Given any  $(e, d)$ -edge-depth-robust DAG  $G$  with  $n$  nodes and maximum degree  $\delta$  we can construct a DAG  $G'$  with  $n \times |M_\delta|$  nodes and constant indegree that is  $(e/2, d \cdot d_\delta)$ -depth robust.*

**Proof (sketch).** Instead of replacing each node  $v \in G$  with a copy of  $M_{\delta(v)}$ , we instead replace each node with a copy of  $M_{\delta, v} := M_\delta$ , attaching the edges same way as in Construction 4. Thus the transformed graph  $G'$  has  $|V(G)| \times |M_\delta|$  nodes and constant indegree. Let  $S \subset V(G')$  be a set of nodes that we will remove from  $G'$ . By Claim 29, there exists a path  $P$  in  $G' - S$  that passes through  $d$  metanodes  $M_{\delta, v_1}, \dots, M_{\delta, v_d}$ . Since  $M_\delta$  is maximally ST-robust with depth  $d_\delta$  the sub-path  $P_i = P \cap M_{\delta, v_i}$  through each metanode has length  $|P_i| \geq d_\delta$ . Thus, the total length of the path is at least  $\sum_i |P_i| \geq d \cdot d_\delta$ . ◀

► **Corollary 8** (of Theorem 5). *Let  $\epsilon > 0$  be any fixed constant. Given any family  $\{G_m\}_{m=1}^\infty$  of  $(e_m, d_m)$ -edge-depth-robust DAGs  $G_m$  with  $m$  nodes and maximum indegree  $\delta_m$  then for some constants  $c_1, c_2 > 0$  we can construct a family  $\{H_m\}_{m=1}^\infty$  of DAGs such that each DAG  $H_m$  is  $(e_m/2, d_m \cdot \delta_m^{1-\epsilon})$ -depth robust,  $H_m$  has maximum indegree at most  $c_2$  (constant) and at most  $|V(H_m)| \leq c_1 m \delta_m$  nodes.*

**Proof (sketch).** This follows immediately from Corollary 7 and from our construction of a family  $\mathbb{M}_\epsilon = \{M_{k, \epsilon}\}_{k=1}^\infty$  of max ST-Robust graphs with depth  $d_k > k^{1-\epsilon}$  and constant indegree. ◀

► **Corollary 9** (of Theorem 5). *Let  $\{e_m\}_{m=1}^\infty$  and  $\{d_m\}_{m=1}^\infty$  be any sequence. If there exists a family  $\{G_m\}_{m=1}^\infty$  of  $(e_m, d_m)$ -edge-depth-robust graphs, where each DAG  $G_m$  has  $m$  edges, then there is a corresponding family  $\{H_n\}_{n=1}^\infty$  of constant indegree DAGs such that each  $H_n$  has  $n$  nodes and is  $(\Omega(e_n), \Omega(d_n))$ -depth-robust.*

The original Grate’s construction [14],  $G$ , has  $N = 2^n$  nodes and  $m = n2^n$  edges and for any  $s \leq n$ , and is  $(s2^n, \sum_{j=0}^s \binom{N}{j})$ -edge-depth-robust. For node depth-robustness we only had matching constructions when  $s = O(1)$  [2, 3] and  $s = \Omega(\log N)$  [14] – no comparable lower bounds were known for intermediate  $s$ .

► **Corollary 10** (of Theorem 5). *There is a family of constant indegree graphs  $\{G_n\}$  such that  $G_n$  has  $O(N = 2^n)$  nodes and  $G_n$  is  $(sN/(2n), \sum_{j=0}^s \binom{N}{j})$ -edge-depth-robust for any  $1 \leq s \leq \log n$*

In particular, setting  $s = \log \log n$  and applying the indegree reduction from Theorem 5, we see that the transformed graph  $G'$  has constant indegree,  $N' = O(n2^n)$  nodes, and is  $(\frac{N' \log \log N'}{\log N'}, \frac{N'}{(\log N')^{1+\log \log N'}})$ -depth-robust. Blocki et al. [5] showed that if there exists a node depth robust graph with  $e = \Omega(N \log \log N / \log N)$  and  $d = \Omega(N \log \log N / \log N)$  then

one can obtain another constant indegree graph with pebbling cost  $\Omega(N^2 \log \log N / \log N)$  which is optimal for constant indegree graphs. We conjecture that the graphs in [8] are sufficiently edge depth robust to meet these bounds after being transformed by our reduction.

### 3 ST Robustness

In this section we show how to construct maximally ST-robust graphs with constant indegree and linear size. We first introduce some of the technical building blocks used in our construction including superconcentrators [10, 13, 16] and grates [14]. Using these building blocks we then provide a randomized construction of a  $c_1$ -maximally ST-robust DAG with linear size and constant indegree for some constant  $c_1 > 0$  – sampled graphs are  $c_1$ -maximally ST-robust DAG with high probability. Finally, we use  $c_1$ -maximally ST-robust DAGs to construct a family of maximally ST-robust graphs with linear size and constant indegree.

#### 3.1 Technical Ingredients

We now introduce other graph properties that will be useful for constructing ST-robust graphs.

##### Grates

A DAG  $G = (V, E)$  with  $n$  inputs  $I$  and  $n$  outputs  $O$  is called a  $(c_0, c_1)$ -grate if for any subset  $S \subset V$  of size  $|S| \leq c_0 n$  at least  $c_1 n^2$  input output pairs  $(x, y) \in I \times O$  remain connected by a directed path from  $x$  to  $y$  in  $G - S$ . Schnitger [14] showed how to construct  $(c_0, c_1)$ -grates with  $O(n)$  nodes and constant indegree for suitable constants  $c_0, c_1 > 0$ . The notion of an maximally ST-robust graph is a strictly stronger requirement since there is no requirement on which pairs are connected. However, we show that a slight modification of Schnitger’s [14] construction is a  $(cn, n/2)$ -ST-robust for a suitable constant  $c$ . We then transform this graph into a  $c_1$ -maximally ST-robust graph by sandwiching it in between two superconcentrators. Finally, we show how to use several  $c_1$ -maximally ST-robust graphs to construct a maximally ST-robust graph.

##### Superconcentrators

We say that a directed acyclic graph  $G = (V, E)$  with  $n$  input vertices and  $n$  output vertices is an  **$n$ -superconcentrator** if for any  $r$  inputs and any  $r$  outputs,  $1 \leq r \leq n$ , there are  $r$  vertex-disjoint paths in  $G$  connecting the set of these  $r$  inputs to these  $r$  outputs. We note that there exists linear size, constant indegree superconcentrators [10, 13, 16] and we use this fact throughout the rest of the paper. For example, Pippenger [13] constructed an  $n$ -superconcentrator with at most  $41n$  vertices and indegree at most 16.

##### Connectors

We say that an  $n$ -superconcentrator is an  **$n$ -connector** if it is possible to specify which input is to be connected to which output by vertex disjoint paths in the subsets of  $r$  inputs and  $r$  outputs. Connectors and superconcentrators are potential candidates for ST-robust graphs because of their highly connective properties. In fact, we can prove that any connectors  **$n$ -connector** is maximally ST-robust – the proof of Theorem 11 can be found in the appendix. While we have constructions of  **$n$ -connector** graphs these graphs have  $O(n \log n)$  vertices and indegree of 2, an information theoretic technique of Shannon [15] can be used to

prove that any  $n$ -connector with constant indegree requires *at least*  $\Omega(n \log n)$  vertices – see discussion in the appendix. Thus, we cannot use  $n$ -connectors to build linear sized ST-robust graphs. However, Shannon’s information theoretic argument does not rule out the existence of linear size ST-robust graphs.

► **Theorem 11.** *If  $G$  is an  $n$ -connector, then  $G$  is  $(k, n - k)$ -ST-robust, for all  $1 \leq k \leq n$ .*

### 3.2 Linear Size ST-robust Graphs

ST-robust graphs have similar connective properties to connectors, so a natural question to ask is whether ST-robust graphs with constant indegree require  $\Omega(n \log n)$  vertices. In this section, we show that linear size ST-robust graphs exist by showing that a modified version of the Grates construction [14] becomes  $c$ -maximally ST-robust when sandwiched between two superconcentrators for some constant  $c$ .

In the proof of Theorem A in [14], Schnitger constructs a family of DAGs  $(H_n | n \in N)$  with constant indegree  $\delta_H$ , where  $n$  is the number of nodes and  $H_n$  is  $(cn, n^{2/3})$ -depth-robust, for suitable constant  $c > 0$ . We construct a similar graph  $G_n$  as follows:

► **Construction 12** ( $G_n$ ). *We begin with  $H_n^1, H_n^2$  and  $H_n^3$ , three isomorphic copies of  $H_n$  with disjoint vertex sets  $V_1, V_2$  and  $V_3$ . For each top vertex  $v \in V_3$  sample  $\tau$  vertices  $x_1^v, \dots, x_\tau^v$  independently and uniformly at random from  $V_2$  and for each  $i \leq \tau$  add each directed edge  $(x_i^v, v)$  to  $G_n$  to connect each of these sampled nodes to  $v$ . Similarly, for each node vertex  $u \in V_2$  sample  $\tau$  vertices  $x_1^u, \dots, x_\tau^u$  from  $V_1$  independently and uniformly at random and add each directed edge  $(x_i^u, u)$  to  $G_n$ . Note that  $\text{indeg}(G_n) \leq \text{indeg}(H_n) + \tau$ .*

Schnitger’s construction only utilizes two isomorphic copies of  $H_n$  and the edges connecting  $H_n^1$  and  $H_n^2$  a sampled by picking  $\tau$  random permutations. In our case the analysis is greatly simplified by picking the edges uniformly and we will need three layers to prove ST-robustness. We will use the following lemma from the Grates paper as a building block. A proof of Lemma 13 is included in the appendix for completeness.

► **Lemma 13** ([14]). *For some suitable constant  $c > 0$  any any subset  $S$  of  $cn/2$  vertices of  $G_n$  the graph  $H_n^1 - S$  contains  $k = cn^{1/3}/2$  vertex disjoint paths  $A_1, \dots, A_k$  of length  $n^{2/3}$  and  $H_n^2 - S$  contains  $k$  vertex disjoint paths  $B_1, \dots, B_k$  of the same length.*

We use Lemma 13 to help establish our main technical Lemma 14. We sketch the proof of Lemma 14 below. A formal proof can be found in Appendix B.

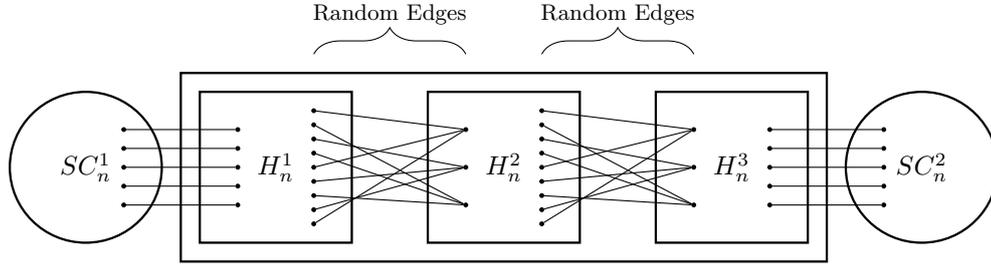
► **Lemma 14.** *Let  $G_n$  be defined as in Construction 12. Then for some constants  $c > 0$ , with high probability  $G_n$  has the property that for all  $S \subset V(G_n)$  with  $|S| = cn/2$  there exists  $A \subseteq V(H_n^1)$  and  $B \subseteq V(H_n^3)$  such that for every pair of nodes  $u \in A$  and  $v \in B$  the graph  $G_n - S$  contains a path from  $u$  to  $v$  and  $|A|, |B| \geq 9cn/40$ .*

**Proof (sketch).** Fixing any  $S$  we can apply Lemma 13 to find  $k := cn^{1/3}/2$  vertex disjoint paths  $P_{1,S}^i, \dots, P_{k,S}^i$  in  $H_n^i$  of length  $n^{2/3}$  for each  $i \leq 3$ . Here,  $c$  is the constant from Lemma 13. Let  $U_{j,S}^i$  be the upper half of the  $j$ -th path in  $H_n^i$  and  $L_{j,S}^i$  be the lower half and define the event  $BAD_{i,S}^{upper}$  to be the event that there exists at least  $k/10$  indices  $j \leq k$  s.t.,  $U_{j,S}^i$  is disconnected from  $L_{i,S}^3$ . We construct  $B$  by taking the union of all of upper paths  $U_{i,S}^3$  in  $H_n^3$  for each non-bad (upper) indices  $i$ . Similarly, we define  $BAD_{i,S}^{lower}$  to be the event that there exists at least  $k/10$  indices  $j \leq k$  s.t.  $U_{i,S}^1$  is disconnected from  $L_{j,S}^2$  and we construct  $A$  by taking the union of all of the lower paths  $L_{i,S}^1$  in  $H_n^1$  for each non-bad (lower) indices  $i$ . We can now argue that any pair of nodes  $u \in A$  and  $v \in B$  is connected by invoking

the pigeonhole principle i.e., if  $u \in L_{i,S}^1$  and  $v \in U_{i',S}^3$  for good indices  $i$  and  $i'$  then there exists some path  $P_j^2$  in the middle layer  $H_n^2$  which can be used to connect  $u$  to  $v$ . We still need to argue that  $|A|, |B| \geq cn/3$  for some constant  $c$ . To lower bound  $|B|$  we introduce the event  $BAD_S = |\{i : BAD_{i,S}^{upper}\}| > \frac{k}{10}$  and note that unless  $BAD_S$  occurs we have  $|B| \geq (9k/10)n^{2/3}/2 = 9cn/40$ . Finally, we show that  $\mathbb{P}[BAD_S]$  is very small and then use union bounds to show that, for a suitable constant  $\tau$ , the probability  $\mathbb{P}[\exists SBAD_S]$  becomes negligibly small. A symmetric argument can be used to show that  $|A| \geq 9cn/40$ . ◀

We now use  $G_n$  to construct  $c$ -maximally ST-robust graphs with linear size.

► **Construction 15** ( $M_n$ ). We construct the family of graphs  $M_n$  as follows: Let the graphs  $SC_n^1$  and  $SC_n^2$  be linear sized  $n$ -superconcentrators with constant indegree  $\delta_{SC}$  [13], and let  $H_n^1, H_n^2$  and  $H_n^3$  be defined and connected as in  $G_n$ , where every output of  $SC_n^1$  is connected to a node in  $H_n^1$ , every node of  $H_n^3$  is connected to an input of  $SC_n^2$ .



■ **Figure 2** A diagram of the constant indegree, linear sized, ST-robust graph  $M_n$ .

► **Theorem 16.** There exists a constant  $c' > 0$  such that for all sets  $S \subset V(M_n)$  with  $|S| \leq c'n/2$ ,  $M_n$  is  $(|S|, n - |S|)$ -ST-robust, with  $n$  inputs and  $n$  outputs and constant indegree.

**Proof.** Let  $c' = 9c/40$ , where  $c$  is the constant from  $G_n$ . Consider  $M_n - S$ . Then because  $|S \cap (H_n^1 \cup H_n^2)| \leq |S| \leq c'n/2 \leq cn/2$ , by Lemma 14 with a high probability there exists sets  $A$  in  $H_n^1$  and  $B$  in  $H_n^3$  with  $|A|, |B| \geq \frac{9}{10}k\frac{n^{2/3}}{2} = \frac{9}{40}cn = c'n$ , such that every node in  $A$  connects to every node in  $B$ . By the properties of superconcentrators, the size of the set  $BAD_1$  of inputs  $u$  in  $SC_n^1$  that can't reach any node in  $A$  in  $M_n - S$ . We claim that  $|BAD_1| \leq |S| \leq c'n$ . Assume for contradiction that  $|BAD_1| > |S|$  then  $SC_n^1$  contains at least  $\min\{|BAD_1|, |A|\} > |S|$  node disjoint paths between  $BAD_1$  and  $A$ . At least one of these node disjoint paths does not intersect  $S$  which contradicts the definition of  $BAD_1$ . Similarly, we can bound the size of  $BAD_2$ , the set of outputs in  $SC_n^2$  which are not reachable from any node in  $B$ . Given any input  $u \notin BAD_1$  of  $SC_n^1$  and any output  $v \notin BAD_2$  of  $SC_n^2$  we can argue that  $u$  is connected to  $v$  in  $M_n - S$  since we can reach some node  $x \in A$  from  $u$  and  $v$  can be reached from some node  $y \in B$  and any such pair  $x, y$  is connected by a path in  $M_n - S$ . It follows that  $M_n$  is  $(|S|, n - |S|)$ -ST-robust. ◀

► **Corollary 17** (of Theorem 16). For all  $\epsilon > 0$ , there exists a family of DAGs  $\mathbb{M} = \{M_n^\epsilon\}_{n=1}^\infty$ , where each  $M_n^\epsilon$  is a  $c$ -maximally ST-robust graphs with  $|V(M_n)| \leq c_\epsilon n$ ,  $\text{indegree}(M_n) \leq c_\epsilon$ , and depth  $d = n^{1-\epsilon}$ .

**Proof (sketch).** In the proof of Lemma 13, we used  $(cn, n^{2/3})$ -depth robust graphs. When considering the paths  $A_i$  and  $B_j$ , we were considering connecting the upper half of one path to the lower half of another. Thus, after we remove nodes from  $M_n$ , there exists a path of

length at least  $n^{2/3}$  that connects any remaining input to any remaining output. Thus  $M_n$  is  $c$ -maximally ST-robust with depth  $d = n^{2/3}$ . In [14], Schnitger provides a construction that is  $(cn, n^{1-\epsilon})$ -depth robust for all constant  $\epsilon > 0$ . By the same arguments we used in this section, we can construct  $c$ -maximally ST-robust graphs with depth  $d = n^{1-\epsilon}$ , where the constant  $c$  depends on  $\epsilon$ . ◀

### 3.3 Constructing Maximal ST-Robust Graphs

In this section, we construct maximal ST-robust graphs, which are 1-maximally ST-robust, from  $c$ -maximally ST-robust graphs. We give the following construction:

▶ **Construction 18** ( $\mathbb{O}(M_n)$ ). *Let  $M_n$  be a  $c$ -maximally ST-robust graph on  $O(n)$  nodes. Let  $O$  be a set  $o_1, o_2, \dots, o_n$  of  $n$  output nodes and let  $I$  be a set  $i_1, i_2, \dots, i_n$  of  $n$  input nodes. Let  $S_j$  for  $1 \leq j \leq \lceil \frac{1}{c} \rceil$  be a copy of  $M_n$  with outputs  $o_1^j, o_2^j, \dots, o_n^j$  and inputs  $i_1^j, i_2^j, \dots, i_n^j$ . Then for all  $1 \leq j \leq n$  and for all  $1 \leq k \leq n$ , add a directed edge from  $i_k$  to  $i_k^j$  and from  $o_k^j$  to  $o_k$ .*

Because we connect  $\lceil \frac{1}{c} \rceil$  copies of  $M_n$  to the output nodes,  $\mathbb{O}(M_n)$  has indegree  $\max\{\delta, \lceil \frac{1}{c} \rceil\}$ , where  $\delta$  is the indegree of  $M_n$ . Also, if  $M_n$  has  $kn$  nodes, then  $\mathbb{O}(M_n)$  has  $(k\lceil \frac{1}{c} \rceil + 2)n$  nodes. We now show that  $\mathbb{O}(M_n)$  is a maximal ST-robust graph.

▶ **Theorem 19.** *Let  $M_n$  be a  $c$ -maximally ST-robust graph. Then  $\mathbb{O}(M_n)$  is a maximal ST-robust graph.*

**Proof.** Let  $R \subset V(\mathbb{O}(M_n))$  with  $|R| = k$ . Let  $R = R_I \cup R_M \cup R_O$ , where  $R_I = R \cap I$ ,  $R_O = R \cap O$ , and  $R_M = R \cap \left(\bigcup_{i=1}^{\lceil 1/c \rceil} S_i\right)$ . Consider  $\mathbb{O}(M_n) - R$ . We see that  $|R_M| \leq k$ , so by the Pidgeonhole Principal at least one  $S_j$  has less than  $cn$  nodes removed, say it has  $t$  nodes removed for  $t \leq cn$ . Hence  $t \leq |R_M|$ . Since  $S_j$  is  $c$ -max ST-robust there exists a subgraph  $H$  of  $S_j - R$  containing  $n - t$  inputs and  $n - t$  outputs such that every input is connected to all of the outputs. Let  $H'$  be the subgraph induced by the nodes in  $V(H) \cup I' \cup O'$ , where  $I' = \{(i_a, i_a^b) | i_a^b \in H\}$  and  $O' = \{(o_a^b, o_a) | o_a^b \in H\}$ .

▷ **Claim 20.** The graph  $H'$  contains at least  $n - k$  inputs and  $n - k$  outputs and there is a path between every pair of input and output nodes.

**Proof.** The set  $|I \setminus I'| \leq |I \cap R| + |V(S_j) \cap R| \leq |R| \leq k$ . Similarly,  $|O \setminus O'| \leq |O \cap R| + |V(S_j) \cap R| \leq |R| \leq k$ . Let  $v \in I'$  be some input. By the connectivity of  $H$ ,  $v$  can reach all of the outputs in  $O'$ . Thus there is a path between every pair of input and output nodes. ◀

Thus  $\mathbb{O}(M_n)$  is  $(k, n - k)$ -ST-robust for all  $1 \leq k \leq n$ . Therefore  $\mathbb{O}(M_n)$  is a maximal ST-robust graph. ◀

▶ **Corollary 21** (of Theorem 19). *For all  $\epsilon > 0$ , there exists a family  $\mathbb{M}^\epsilon = \{M_k^\epsilon\}_{k=1}^\infty$  of maximal ST-robust graphs of depth  $d = n^{1-\epsilon}$  such that  $|V(M_k^\epsilon)| \leq c_\epsilon n$  and  $\text{indegree}(M_k^\epsilon) \leq c_\epsilon$ .*

**Proof.** Apply Construction 18 to the family graphs  $\mathbb{M}^\epsilon = \{M_k^\epsilon\}_{k=1}^\infty$  from Corollary 17. Then by Theorem 19, the family of graphs  $\{\mathbb{O}(M_k^\epsilon)\}_{k=1}^\infty$  is the desired family. ◀

## 4 Applications of ST-Robust Graphs

As outlined previously maximally ST-Robust graphs give us a tight connection between edge-depth robustness and node-depth robustness. Because edge-depth-robust graphs are often easier to design than node-depth robust graphs [14] this gives us a fundamentally new approach to construct node-depth-robust graphs. Beyond this exciting connection we can also use ST-robust graphs to construct perfectly tight proofs of space [9, 12] and asymptotically superior wide-block labeling functions [6].

### 4.1 Tight Proofs of Space

In Proof of Space constructions [12] we want to find a DAG  $G = (V, E)$  with small indegree along with a challenge set  $V_C \subseteq V$ . Intuitively, the prover will label the graph  $G$  using a hash function  $H$  (often modeled as a random oracle in security proofs) such that a node  $v$  with parents  $v_1, \dots, v_\delta$  is assigned the label  $L_v = H(L_{v_1}, \dots, L_{v_\delta})$ . The prover commits to storing  $L_v$  for each node  $v$  in the challenge set  $V_C$ . The pair  $(G, V_C)$  is said to be  $(s, t, \epsilon)$ -hard if for any subset  $S \subseteq V$  of size  $|S| \leq s$  at least  $(1 - \epsilon)$  fraction of the nodes in  $V_C$  have depth  $\geq t$  in  $G - S$  – a node  $v$  has depth  $\geq t$  in  $G - S$  if there is a path of length  $\geq t$  ending at node  $v$ . Intuitively, this means that if a cheating prover only stores  $s \leq |V_C|$  labels and is challenged to reproduce a random label  $L_v$  with  $v \in V_C$  that, except with probability  $\epsilon$ , the prover will need at least  $t$  sequential computations to recover  $L_v$  – as long as  $t$  is sufficiently large the verifier the cheating prover will be caught as he will not be able to recover the label  $L_v$  in a timely fashion. Pietrzak argued that  $(s, t, \epsilon)$ -hard graphs translate to secure Proofs of Space in the parallel random oracle model [12].

We want  $G$  to have small indegree  $\delta(G)$  (preferably constant) as the prover will need  $O(N\delta(G))$  steps and we want  $|V_C| = \Omega(N)$  and we want  $\epsilon$  to be small while  $s, t$  should be larger. Pietrzak [12] proposed to let  $G_\epsilon$  be an  $\epsilon$ -extreme depth-robust graph with  $N' = 4N$  nodes and to let  $V_C = [3N + 1, 4N]$  be the last  $N$  nodes in this graph. An  $\epsilon$ -extreme depth-robust graph with  $N'$  nodes is  $(e, d)$ -depth robust for any  $e + d \leq (1 - \epsilon)N'$ . Such a graph is  $(s, N, s/N + 4\epsilon)$ -hard for any  $s \leq N$ . Alwen et al. [4] constructed  $\epsilon$ -extreme depth-robust graphs with indegree  $\delta(G) = O(\log N)$  though the hidden constants seem to be quite large. Thus, it would take time  $O(N \log N)$  for the prover to label the graph  $G$ . We remark that  $\epsilon = s/|V_C|$  is the tightest possible bound one can hope for as the prover can always store  $s$  labels from the set  $V_C$ .

We remark that if we take  $V_C$  to be any subset of output nodes from a maximally ST-robust graph and overlay an  $(e = s, d = t)$ -depth robust graph over the input nodes then the resulting graph will be  $(s, t, \epsilon = s/|V_C|)$ -hard – optimally tight in  $\epsilon$ . In particular, given a DAG  $G = (V = [N], E)$  with  $N$  nodes define the overlay graph  $H_G$  by starting with a maximally ST-Robust graph with  $|V|$  inputs  $I = \{x_1, \dots, x_{|V|}\}$  and  $|V|$  outputs  $O$  then for every directed edge  $(u, v) \in E(G)$  we add the directed edge  $(x_u, x_v)$  to  $E(H_G)$  and we specify a target set  $V_C \subseteq O$ . Fisch [9] gave a practical construction of  $(G, V_C)$  with indegree  $O(\log N)$  that is  $(s, N, \epsilon = s/N + \epsilon')$ -hard. The constant  $\epsilon'$  can be arbitrarily small though the number of nodes in the graph scales with  $O(N \log 1/\epsilon')$ . Utilizing ST-robust graphs we fix  $\epsilon' = 0$  without increasing the size of the graph<sup>1</sup>.

<sup>1</sup> As a disclaimer we are not claiming that our construction would be more efficient than [9] for practical parameter settings.

► **Theorem 22.** *If  $G$  is  $(e, d)$ -depth robust then the pair  $(H_G, V_C)$  specified above is  $(s, t = d + 1, s/|V_C|)$ -hard for any  $s \leq e$ .*

**Proof.** Let  $S$  be a subset of  $|S| \leq s$  nodes in  $H_G$ . By maximal ST-robustness we can find a set  $A$  of  $N - |S|$  inputs and  $B$  of  $N - |S|$  outputs such that every pair of nodes  $u \in A$  and  $v \in B$  are connected in  $H_G - S$ . We also note since  $A$  contains all but  $s$  nodes from  $G$  that some node  $u \in A$  is the endpoint of a path of length  $t$  by  $(s, t)$ -depth-robustness of  $G$ . Since  $u$  is connected to *every* node in  $B$  this means that every node  $v \in B$  is the endpoint of a path of length *at least*  $t + 1$ . ◀

This result immediately leads to a  $(s, N^{1-\epsilon}, s/N)$ -hard pair for any  $s \leq N$  which the prover can label in  $O(N)$  time as the DAG  $G$  has constant indegree. We expect that in many settings  $t = N^{1-\epsilon}$  would be sufficiently large to ensure that a cheating prover is caught with probability  $s/N$  after each challenge i.e., if the verifier expects a response within 3 seconds, but it would take longer to evaluate the hash function  $H$   $N^{1-\epsilon}$  sequential times.

► **Corollary 23.** *For any constant  $\epsilon > 0$  there is a constant indegree DAG  $G$  with  $O(N)$  nodes along with a target set  $V_C \subseteq V(G)$  of  $N$  nodes such that the pair  $(G, V_C)$  is  $(s, t = N^{1-\epsilon}, s/N)$ -hard for any  $s \leq N$ .*

**Proof (sketch).** Let  $G$  be an  $(N, N^{1-\epsilon})$ -depth robust graph with  $N' = O(N)$  nodes and constant indegree from [14]. We can then take  $V_C$  to be any subset of  $N$  output nodes in the graph  $H_G$  and apply Theorem 22. ◀

If one does not want to relax the requirement that  $t = \Omega(N)$  then we can provide a perfectly tight construction with  $O(N \log N)$  nodes and constant indegree. Since the graph has constant indegree it will take  $O(N \log N)$  work for the prover to label the graph. This is equivalent to [12], but with perfect tightness  $\epsilon = s/N$ .

► **Corollary 24.** *For any constant  $\epsilon > 0$  there is a constant indegree DAG  $G$  with  $N' = O(N \log N)$  nodes along with a target set  $V_C \subseteq V(G)$  of  $N$  nodes such that the pair  $(G, V_C)$  is  $(s, t, s/N)$ -hard for any  $s \leq N$ .*

**Proof (sketch).** Let  $G$  be an  $(N, N \log N)$ -depth robust graph with  $N' = O(N \log N)$  nodes and constant indegree from [2]. We can then take  $V_C$  to be any subset of  $N$  output nodes in the graph  $H_G$  and apply Theorem 22. ◀

Finally, if we want to ensure that the graph only has  $O(N)$  nodes and  $t = \Omega(N)$  we can obtain a perfectly tight construction with indegree  $\delta(G) = O(\log N)$ .

► **Corollary 25.** *For any constant  $\epsilon > 0$  there is a DAG  $G$  with  $O(N)$  nodes and indegree  $\delta(G) = O(\log N)$  along with a target set  $V_C \subseteq V(G)$  of  $N$  nodes such that the pair  $(G, V_C)$  is  $(s, N, s/N)$ -hard for any  $s \leq N$ .*

**Proof (sketch).** Let  $G$  be an  $(N, N)$ -depth robust graph with  $N' = 3N$  nodes from [4]. We can then take  $V_C$  to be any subset of  $N$  output nodes in the graph  $H_G$  and apply Theorem 22. ◀

## 4.2 Wide-Block Labeling Functions

Chen and Tessaro [6] introduced source-to-sink depth robust graphs as a generic way of obtaining a wide-block labeling function  $H_{\delta, W} : \{0, 1\}^{\delta W} \rightarrow \{0, 1\}^W$  from a small-block function  $H_{fix} : \{0, 1\}^{2L} \rightarrow \{0, 1\}^L$  (modeled as an ideal primitive). In their proposed

approach one transforms a graph  $G$  with indegree  $\delta$  and into a new graph  $G'$  by replacing every node with a source-to-sink depth-robust graph. Labeling a graph  $G$  with a wide-block labeling function is now equivalent to labeling  $G'$  with the original labeling function  $H_{fix}$ . The formal definition of Source-to-Sink-Depth-Robustness is presented below:

► **Definition 26** (Source-to-Sink-Depth-Robustness (SSDR) [6]). *A DAG  $G = (V, E)$  is  $(e, d)$ -source-to-sink-depth-robust (SSDR) if and only if for any  $S \subset V$  where  $|S| \leq e$ ,  $G - S$  has a path (with length at least  $d$ ) that starts from a source node of  $G$  and ends up in a sink node of  $G$ .*

If  $G$  is  $(e, d)$ -depth robust and  $G'$  is constructed by replacing every node  $v$  in  $G$  with a  $(e^*, d^*)$ -source-to-sink-depth-robust (SSDR) and orienting incoming (resp. outgoing) edges into the sources (resp. out of the sinks) then the graph  $G'$  is  $(ee^*, dd^*)$ -depth robust [6] and has cumulative pebbling complexity at least  $ed(e^*d^*)$  [3]. The SSDR graphs constructed in [6] are  $(\frac{K}{4}, \frac{\delta K^2}{2})$ -SSDR with  $O(\delta K^2)$  vertices and constant indegree. They fix  $K := W/L$  as the ratio between the length of outputs for  $H_{\delta, W} : \{0, 1\}^{\delta W} \rightarrow \{0, 1\}^W$  and the ideal primitive  $H_{fix}$ . Their graph has  $\delta K$  source nodes for a tunable parameter  $\delta \in \mathbb{N}$ ,  $O(\delta K^2)$  vertices and constant indegree. Ideally, since we are increasing the number of nodes by a factor of  $\delta K^2$  we would like to see the cumulative pebbling complexity increase by a quadratic factor of  $\delta^2 K^4$ . Instead, if we start with an  $(e, d)$ -depth robust graph with cumulative pebbling complexity  $O(ed)$  their final graph  $G'$  has cumulative pebbling complexity  $ed \times \frac{\delta K^3}{8}$ . Chen and Tessaro left the problem of finding improved source-to-sink depth-robust graphs as an open research question.

Our construction of ST-robust graphs can asymptotically<sup>2</sup> improve some of their constructions, specifically their constructions of source-to-sink-depth-robust graphs and wide-block labeling functions.

► **Theorem 27.** *Let  $G$  be a maximal ST-robust graph with depth  $d$  and  $n$  inputs and outputs. Then  $G$  is an  $(n - 1, d)$ -SSDR graph.*

**Proof.** By the maximal ST-robustness property,  $n - 1$  arbitrary nodes can be removed from  $G$  and there will still exist at least one input node that is connected to at least one output node. Since  $G$  has depth  $d$ , the path between the input node and output node must have length at least  $d$ . ◀

By applying Theorem 27 to the construction in Corollary 19, we can construct a family of  $(\delta K, (\delta K)^{1-\epsilon})$ -SSDR graphs with  $O(\delta K)$  nodes and constant indegree and  $\delta K$  sources. In this case the cumulative pebbling complexity of our construction would be already be  $ed \times \delta^2 K^{2-\epsilon}$  which is much closer to the quadratic scaling that we would ideally like to see. We are off by just  $K^\epsilon$  for a constant  $\epsilon > 0$  that can be arbitrarily small. To make the comparison easier we could also applying Theorem 27 to obtain a family of  $(\delta K^2, (\delta K^2)^{1-\epsilon})$ -SSDR graphs with  $O(\delta K^2)$ -nodes and constant indegree. While the size of the SSDR matches [6] our new graph is  $(e\delta K^2, d(\delta K^2)^{1-\epsilon})$ -depth robust and has cumulative pebbling complexity  $ed \times \delta^{2-\epsilon} K^{4-2\epsilon} \gg ed\delta K^3$ .

<sup>2</sup> While we improve the asymptotic performance we do not claim to be more efficient for practical values of  $\delta, K$ .

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## A Connector Graphs

We say that a directed acyclic graph  $G = (V, E)$  with  $n$  input vertices and  $n$  output vertices is an  **$n$ -connector** if for any *ordered list*  $x_1, \dots, x_r$  of  $r$  inputs and any *ordered list*  $y_1, \dots, y_r$  of  $r$  outputs,  $1 \leq r \leq n$ , there are  $r$  vertex-disjoint paths in  $G$  connecting input node  $x_i$  to output node  $y_i$  for each  $i \leq r$ .

### A.1 Connector Graphs are ST-Robust

We remarked in the paper that any  **$n$ -connector** is maximally ST-robust.

► **Reminder of Theorem 11.** *If  $G$  is an  $n$ -connector, then  $G$  is  $(k, n - k)$ -ST-robust, for all  $1 \leq k \leq n$ .*

**Proof of Theorem 11.** Let  $D \subseteq V(G)$  with  $|D| = k$ . Consider  $G - D$ . Let  $A = \{(s_1, t_1), \dots, (s_m, t_m)\}$ , where the input  $s_i \in S$  is disconnected from the output  $t_i \in T$  in  $G - D$ , or  $s_i \in D$  or  $t_i \in D$ . Let  $B = \emptyset$ .

Perform the following procedure on  $A$  and  $B$ : Pick any pair  $(s_p, t_p) \in A$  and add  $s_p$  and  $t_p$  to  $B$ . Then remove the pair from  $A$  along with any other pair in  $A$  that shares either  $s_p$  or  $t_p$ . Continue until  $A$  is empty.

If we consider the nodes of  $B$  in  $G$ , then there are  $|B|$  vertex-disjoint paths between the pairs in  $B$  by the connector property, and in  $G - D$  at least one vertex is removed from each path. Thus  $|B| \leq k$ , or we have a contradiction.

If  $(s, t) \in G - (D \cup B)$  are an input to output pair, and  $s$  is disconnected from  $t$ , then by the definition of  $A$  and  $B$  we would have a contradiction, since  $(s, t)$  would still be in  $A$ . Thus all of the remaining inputs in  $G - (D \cup B)$  are connected to all the remaining outputs.

Hence, if we let  $H = G - (D \cup B)$ , then  $H$  is a subgraph of  $G$  with at least  $n - k$  inputs and  $n - k$  outputs, and there is a path going from each input of  $H$  to each of its outputs. Therefore,  $G$  is  $(k, n - k)$ -ST-robust for all  $1 \leq k \leq n$ . ◀

### Butterfly Graphs

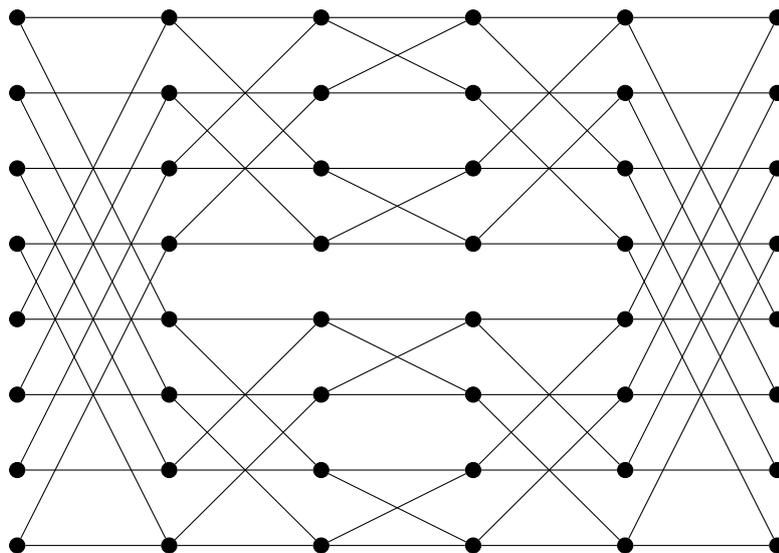
A well known family of constant indegree  $n$ -connectors, for  $n = 2^k$ , are the  $k$ -dimensional butterfly graphs  $B_k$ , which are formed by connecting two FFT graphs on  $n$  inputs back to back. By Theorem 11, the butterfly graph is also a maximally ST-robust graph. However, the butterfly graph has  $\Omega(n \log n)$  nodes and does not yield a ST-robust graph of linear size. Since  $B_k$  has  $O(n \log n)$  vertices and indegree of 2, a natural question to ask is if there exists  $n$ -connectors with  $O(n)$  vertices and constant indegree.

### A.2 Connector Graphs Have $\Omega(n \log n)$ vertices

An information theoretic argument of Shannon [15] rules out the possibility of linear size  $n$ -connectors.

► **Theorem 28** (Shannon [15]). *An  $n$ -connector with constant indegree requires at least  $\Omega(n \log n)$  vertices.*

Intuitively, given a  $n$ -connector with constant indegree with constant indegree and  $m$  edges Shannon argued that we can use the  $n$ -connector to encode any permutation of  $[n]$  using  $m$  bits. In more detail fixing any permutation  $\pi$  we can find  $n$  node disjoint paths from input  $i$  to output  $\pi(i)$ . Because the paths are node disjoint we can encode  $\pi$  simply



■ **Figure 3** The butterfly graph  $B_3$  is both an 8-superconcentrator and an 8-connector. All edges are directed from left to right.

by specifying the subset  $S_\pi$  of directed edges which appear in one of these node disjoint paths. We require at most  $m$  bits to encode  $S_\pi$  and from  $S_\pi$  we can reconstruct the set of node-disjoint paths and recover  $\pi$ . Thus, we must have  $m = \Theta(n \log n)$  since we require  $\log n! = \Theta(n \log n)$  bits to encode a permutation.

We stress that this information theoretic argument breaks down if the graph  $G$  is only ST-robust. We are guaranteed that  $G$  contains a path from input  $i$  to output  $\pi(i)$ , but we are not guaranteed that all of the paths are node disjoint. Thus,  $S_\pi$  is insufficient to reconstruct  $\pi$ .

## B Missing Proofs

► **Reminder of Theorem 5.** *Let  $G$  be an  $(e, d)$ -edge-depth-robust DAG with  $m$  edges. Let  $\mathbb{M}$  be a family of max ST-Robust graphs with constant indegree. Then  $G' = (V', E') = \text{Reduce}(G, \mathbb{M})$  is  $(e/2, d)$ -depth robust. Furthermore,  $G'$  has maximum indegree  $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$ , and its number of nodes is  $\sum_{v \in V(G)} |V(M_{\delta(v)})|$  where  $\delta(v) = \max\{\text{indeg}(v), \text{outdeg}(v)\}$ .*

**Proof of Theorem 5.** We know that each graph in  $\mathbb{M}$  has constant indegree, and that each node  $v$  in  $G$  will be replaced with a graph in  $\mathbb{M}$  with indegree  $\text{indeg}(M_{\delta(v)})$ . Thus  $G'$  has maximum indegree  $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$ . Furthermore, the metanode corresponding to the node  $v$  has size  $|M_{\delta(v)}|$ . Thus  $G'$  has  $\sum_{v \in V(G)} |M_{\delta(v)}|$  nodes.

Let  $S \subset V(G')$  be a set of nodes that we will remove from  $G'$ . For a specific node  $v \in V(G)$  we let  $S_v = S \cap (\{v\} \times V_{\delta(v)})$  denote the subset of nodes deleted from the corresponding metanode. We say that the node  $v \in V(G)$  is *irreparable* with respect to  $S$  if  $|S_v| \geq \delta(v)$ ; otherwise we say that  $v$  is *reparable*. If a node  $v$  is reparable, then because the metanodes are maximally ST-Robust we can find subsets  $I_{v,S}$  and  $O_{v,S}$  (with  $|I_{v,S}|, |O_{v,S}| \geq \delta(v) - |S_v|$ ) such that each input node  $s \in I_{v,S}$  is connected to every output node in  $O_{v,S}$ .

## 64:16 A New Connection Between Node and Edge D.R. Graphs

We say that an edge  $(u, v) \in E(G)$  is *irreparable* with respect if  $u$  or  $v$  is irreparable, or if the corresponding edge  $e' = (u', v') \in E(G')$  has  $u' \notin O_{u,S}$  or  $v' \notin I_{v,S}$ . We let  $S_{irr} \subset E(G)$  be the set of irreparable edges after we remove  $S$  from  $G$ . We begin the proof by first proving two claims.

▷ **Claim 29.** Let  $P$  be a path of length  $d$  in  $G - S_{irr}$ . Then there exists a path of length at least  $d$  in  $G' - S$ .

*Proof.* In  $G - S_{irr}$  we have removed all of the irreparable edges, so any path in the graph contains only repairable edges. By definition, if  $(u, v)$  is a repairable edge, both  $u$  and  $v$  will be repairable, and  $(u, \pi_{out,u}(v)) \in O_{u,S}$  and  $(v, \pi_{in,v}(u)) \in I_{v,S}$ . Thus the edge corresponding to  $(u, v)$  in  $G' - S$  will connect the metanodes of  $u$  and  $v$ , and  $(u, \pi_{out,u}(v))$  connects to every node in  $I_{u,S}$  and  $(v, \pi_{in,v}(u))$  connects to every node in  $O_{v,S}$ . Thus the edges in  $G' - S$  corresponding to the edges in  $P$  form a path of length at least  $d$ . ◁

▷ **Claim 30.** Let  $S_{irr} \subset E(G)$  be the set of irreparable edges with respect to the removed set  $S$ . Then

$$|S_{irr}| \leq 2|S|.$$

*Proof.* If a node  $v$  is repairable with respect to  $S$  then let  $S_{irr,v}^{in} \subseteq E(G)$  (resp.  $S_{irr,v}^{out}$ ) denote the subset of edges  $(u, v) \in E(G)$  (resp.  $(v, u) \in E(G)$ ) that are irreparable because of  $S_v$  i.e., the corresponding edge  $e' = (u', v') \in E(G')$  has  $v' \notin I_{v,S}$  (resp. the corresponding edge  $(v', u') \in E(G')$  has  $v' \notin O_{v,S}$ ). Let  $S_{irr,v} = S_{irr,v}^{in} \cup S_{irr,v}^{out}$ . Similarly, if  $v$  is irreparable we let  $S_{irr,v} = \{(u, v) : (u, v) \in E(G)\} \cup \{(v, u) : (v, u) \in E(G)\}$  denote the set of all of  $v$ 's incoming and outgoing edges. We note that  $|S_{irr}| \leq \sum_v |S_{irr,v}|$  since  $S_{irr} = \bigcup_v S_{irr,v}$  any irreparable edge must be in one of the sets  $S_{irr,v}$ . Now we claim that  $|S_{irr,v}| \leq |S_v|$  where  $S_v = S \cap (\{v\} \times V_{\delta(v)})$  denote the subset of nodes deleted from the corresponding metanode. We now observe that

$$\begin{aligned} |S_{irr,v}| &\leq |S_{irr,v}^{in}| + |S_{irr,v}^{out}| \\ &\leq (\delta(v) - |I_{v,S}|) + (\delta(v) - |O_{v,S}|) \leq 2|S_v|. \end{aligned}$$

The last inequality invokes maximal ST-robustness to show that  $\delta(v) - |O_{v,S}| \leq |S_v|$  and  $\delta(v) - |I_{v,S}| \leq |S_v|$ . If a node  $v$  is irreparable then the subsets  $I_{v,S}$  and  $O_{v,S}$  might be empty since  $\delta(v) - |S_v| \leq 0$ , but it still holds that  $\delta(v) - |O_{v,S}| \leq |S_v|$  and  $\delta(v) - |I_{v,S}| \leq |S_v|$ . Thus, we have

Thus

$$|S_{irr}| \leq \sum_v |S_{irr,v}| \leq \sum_v 2|S_v| \leq 2|S|. \quad \triangleleft$$

► **Reminder of Corollary 7.** (of Theorem 5) *Suppose that there exists a family  $\mathbb{M} = \{M_k\}_{k=1}^{\infty}$  of max ST-Robust graphs with depth  $d_k$  and constant indegree. Given any  $(e, d)$ -edge-depth-robust DAG  $G$  with  $n$  nodes and maximum degree  $\delta$  we can construct a DAG  $G'$  with  $n \times |M_\delta|$  nodes and constant indegree that is  $(e/2, d \cdot d_\delta)$ -depth robust.*

**Proof of Corollary 7 (sketch).** We slightly modify our reduction. Instead of replacing each node  $v \in G$  with a copy of  $M_{\delta(v)}$ , we instead replace each node with a copy of  $M_{\delta,v} := M_\delta$ , attaching the edges same way as in Construction 4. Thus the transformed graph  $G'$  has

$|V(G)| \times |M_\delta|$  nodes and constant indegree. Let  $S \subset V(G')$  be a set of nodes that we will remove from  $G'$ . By Claim 29, there exists a path  $P$  in  $G' - S$  that passes through  $d$  metanodes  $M_{\delta,v_1}, \dots, M_{\delta,v_d}$ . The only difference is that each  $M_{\delta,v_i}$  is maximally ST-robust *with depth*  $d_\delta$  meaning we can assume that the sub-path  $P_i = P \cap M_{\delta,v_i}$  through each metanode has length  $|P_i| \geq d_\delta$ . Thus, the total length of the path is at least  $\sum_i |P_i| \geq d \cdot d_\delta$ . ◀

► **Reminder of Lemma 13 [14].** For some suitable constant  $c > 0$  any any subset  $S$  of  $cn/2$  vertices of  $G_n$  the graph  $H_n^1 - S$  contains  $k = cn^{1/3}/2$  vertex disjoint paths  $A_1, \dots, A_k$  of length  $n^{2/3}$  and  $H_n^2 - S$  contains  $k$  vertex disjoint paths  $B_1, \dots, B_k$  of the same length.

**Proof of Lemma 13 [14].** Consider  $H_n^1 - S$ . Since  $H_n^1$  is  $(cn, n^{2/3})$ -depth-robust and  $|S| = cn/2$ , there must exist a path  $A_1 = (v_1, \dots, v_{n^{2/3}})$  in  $H_n^1 - S$ . Remove all vertices of  $A_1$  and repeat to find  $A_2, \dots$ . Then we finish with  $cn/(2n^{2/3}) = cn^{1/3}/2$  vertex disjoint paths of length  $n^{2/3}$ . We perform the same process on  $H_n^2$  to find the  $B_i$ . ◀

► **Reminder of Lemma 14.** Let  $G_n$  be defined as in Construction 12. Then for some constants  $c > 0$ , with high probability  $G_n$  has the property that for all  $S \subset V(G_n)$  with  $|S| = cn/2$  there exists  $A \subseteq V(H_n^1)$  and  $B \subseteq V(H_n^3)$  such that for every pair of nodes  $u \in A$  and  $v \in B$  the graph  $G_n - S$  contains a path from  $u$  to  $v$  and  $|A|, |B| \geq 9cn/40$ .

**Proof of Lemma 14.** By Lemma 13, we know that in  $G_n - S$  there exists  $k := c'n^{1/3}/2$  vertex disjoint paths  $A_1, \dots, A_k$  in  $H_n^1$  of length  $n^{2/3}$  and  $k$  vertex disjoint paths  $B_1, \dots, B_k$  in  $H_n^2$  of length  $n^{2/3}$ . Here,  $c'$  is the constant from Lemma 13. Let  $U_{j,S}^i$  be the upper half of the  $j$ -th path in  $H_n^i$  and  $L_{j,S}^i$  be the lower half, both of which are relative to the removed set  $S$ .

Now for each  $i \leq k$  define the event  $BAD_{i,S}$  to be the event that there exists  $j \leq k$  s.t.,  $U_{j,S}^1$  is disconnected from  $L_{j,S}^2$ . We now set  $GOOD_S = [k] \setminus \{i : BAD_{i,S}\}$  and define

$$B_S := \bigcup_{i \in GOOD_S} U_{i,S}^2, \quad \text{and} \quad A_S := \bigcup_{i=1}^k L_{i,S}^1.$$

Now we claim that for every node  $u \in A_S$  and  $v \in B_S$  the graph  $G_n - S$  contains a path from  $u$  to  $v$ . Since  $u \in A_S$  we have  $u \in L_{i,S}^1$  for some  $i \leq k$ . Thus, all nodes in  $U_{i,S}^1$  are reachable from  $u$ . Since,  $v \in B_S$  we have  $v \in U_{j,S}^2$  for some good  $j \in GOOD$ . We know that  $v$  is reachable from any node in  $L_{j,S}^2$ . By definition of  $GOOD_S$  there must be an edge  $(x, y)$  from some node  $x \in U_{i,S}^1$  to some node  $y \in L_{j,S}^2$  since we already know that there is a directed path from  $u$  to  $x$  and from  $y$  to  $v$  there is a directed path from  $u$  to  $v$ . Thus, every pair of nodes in  $A_S$  and  $B_S$  are connected.

We have  $|A_S| \geq kn^{2/3} = c'n/2$ . It remains to argue that for any set  $S$  the resulting set  $|B_S| = |GOOD_S|n^{2/3}$  is sufficiently large. Now we define the event

$$BAD_S := |\{i : BAD_{i,S}\}| > \frac{k}{10}.$$

Intuitively,  $BAD_S$  occurs when more than a small fraction of the events  $BAD_{i,S}$  occur. Assuming that  $BAD_S$  never occurs then for any set  $S$  we have

$$|B_S| \geq |GOOD_S|n^{2/3} \geq (9/10)kn^{2/3} = 9c'n/20.$$

Consider, for the sake of finding the probabilities, that  $S$  is fixed before all of the random edges are added to  $G_n$ . We will then union bound over all choices of sets  $S$ . First we consider the probability that a single upper path, say  $U_{1,S}^1$  is disconnected from a particular lower

64:18 A New Connection Between Node and Edge D.R. Graphs

path, say  $L_{1,S}^2$ . There are  $n^{1/3}$  possible lower parts to connect to, and there are  $n^{2/3}/2$  nodes in the upper part that can connect to the lower part, and there are  $\tau$  random edges added from each node in the upper part, so we have that

$$\mathbb{P}\left[U_{1,S}^1 \text{ disconnected from } L_{1,S}^2\right] \leq \left(1 - \frac{1}{2n^{1/3}}\right)^{\tau n^{2/3}/2} \leq \left(\frac{1}{e}\right)^{\tau n^{1/3}/4}.$$

Union bounding over all indices  $j$  we have

$$\mathbb{P}[BAD_{i,S}] \leq k \left(\frac{1}{e}\right)^{\tau n^{1/3}/4} = \left(\frac{1}{e}\right)^{\tau n^{1/3}/4 - \ln k}.$$

We remark that for  $i \neq j$  the event  $BAD_{i,S}$  is independent of  $BAD_{j,S}$  since the  $\tau$  random incoming edges connected to  $L_i^2$  are sampled independently of the edges for  $L_j^2$ .

We will show that the probability of the event  $BAD_S$  is very small and then take a union bound over all possible  $S$  to show our desired result.

$$\begin{aligned} \mathbb{P}[BAD_S] &\leq \binom{k}{k/10} \mathbb{P}[BAD_{1,S} \wedge \dots \wedge BAD_{k/10,S}] \\ &= \binom{k}{k/10} \mathbb{P}[BAD_{1,S}^{upper}]^{k/10} \\ &\leq \binom{k}{k/10} \left[\left(\frac{1}{e}\right)^{\tau n^{1/3}/4 - \ln k}\right]^{k/10} \\ &= \binom{k}{k/10} \left(\frac{1}{e}\right)^{(k\tau n^{1/3} - 4k \ln k)/40}. \end{aligned}$$

Finally, we take the union bound over every possible  $S$  of size  $cn/2$  nodes. Since  $G_n$  has  $2n$  nodes there are at most  $2^{2n} = e^{2n \ln 2}$  such sets. Thus,

$$\mathbb{P}[\exists S \text{ s.t. } BAD_S] \leq e^{2n \ln 2} \mathbb{P}[BAD_S^{upper}] \leq \left(\frac{1}{e}\right)^{(k\tau n^{1/3} - 4k \ln k)/40 - 2n \ln 2}.$$

By selecting a sufficiently large constant like  $\tau = 800/c'$  we can ensure that  $(k\tau n^{1/3} - 4k \ln k)/40 - 2n \ln 2 = 20n - 2n \ln 2 - (k \ln k)/10 \geq n$  so that

$$\mathbb{P}[\exists S \text{ s.t. } BAD_S] \leq 2^{-n}.$$

Thus, except with negligible probability for any  $S$  of size  $cn/2$  the event  $BAD_S$  does not occur for any set  $S$  selected *after*  $G_n$  is sampled. ◀